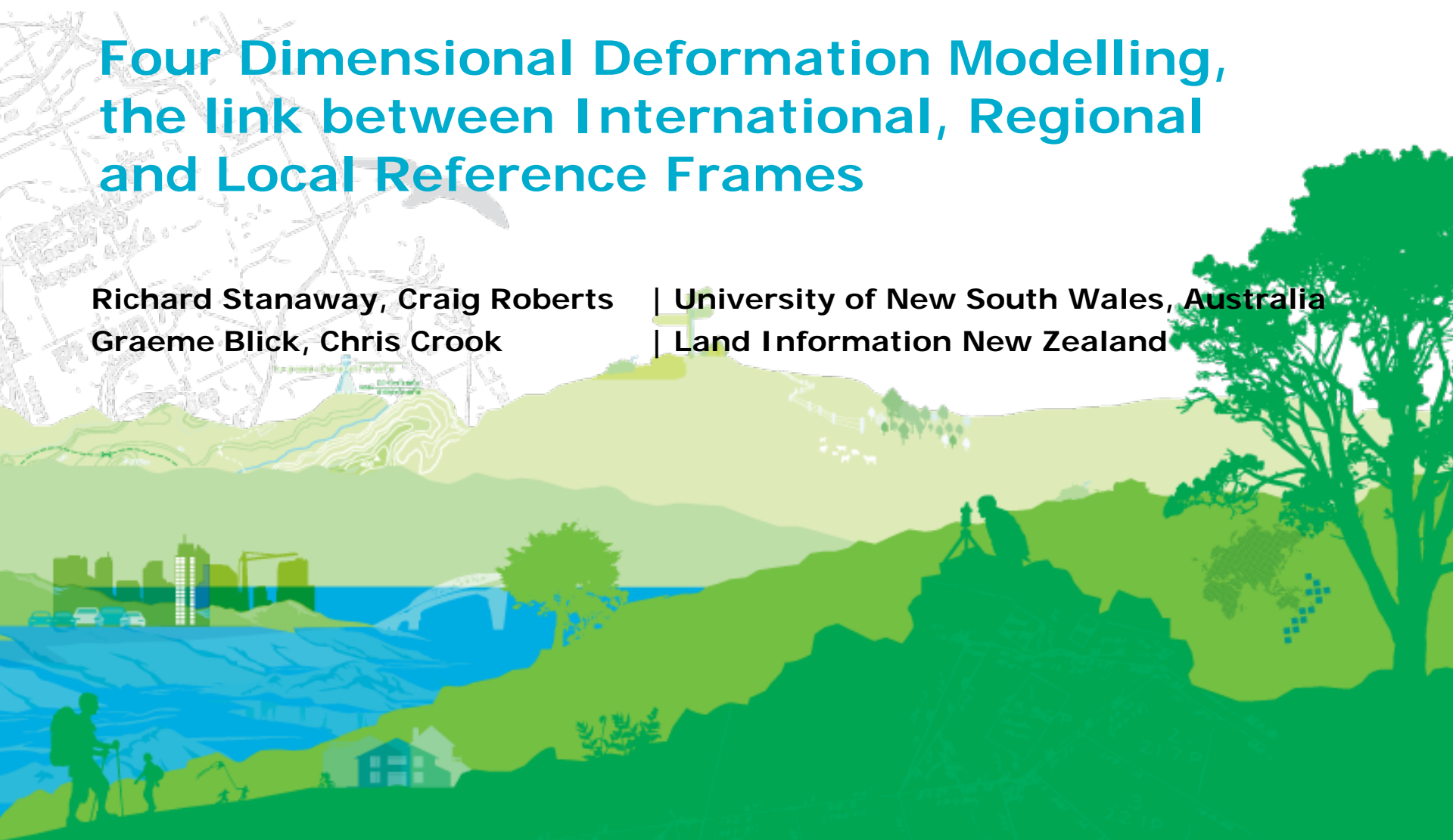


# Four Dimensional Deformation Modelling, the link between International, Regional and Local Reference Frames

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## Global Reference Frames

(e.g. ITRF2008, IGS08, WGS84(G1150))

**Dynamic  
(kinematic)  
NNR-Frame**

GNSS data processing & analysis  
(e.g. PPP, RTK, NRTK, DGPS, Static post-processing)  
Large-scale deformation analysis, GGOS

## Regional Reference Frames

(e.g. EUREF, SIRGAS, NAD83, AFREF, APREF)

**Dynamic  
or semi-  
dynamic  
NNR-Frame or  
plate fixed**

Regional densification of ITRF  
Connectivity between national datums  
Overarching frame for national datums / local reference frames

## Local Reference Frames

(e.g. GDA94, OSGB36, IGM95, NZGD2000)

**Static  
or semi-  
dynamic  
typically plate  
fixed**

Most spatial applications  
(e.g. cadastral, engineering, mapping, precision agriculture, mining, LiDar products)  
terrestrial surveying  
(e.g. TLS, total-station)

**Dynamic (kinematic) NNR-Frame**  
(e.g. ITRF, WGS84)

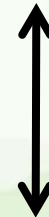
14 – parameter transformation  
or Euler Pole definition

**Dynamic Plate-fixed Frame**  
(e.g. EUREF, NAD83)

7 or 14 – parameter transformation  
and/or deformation model

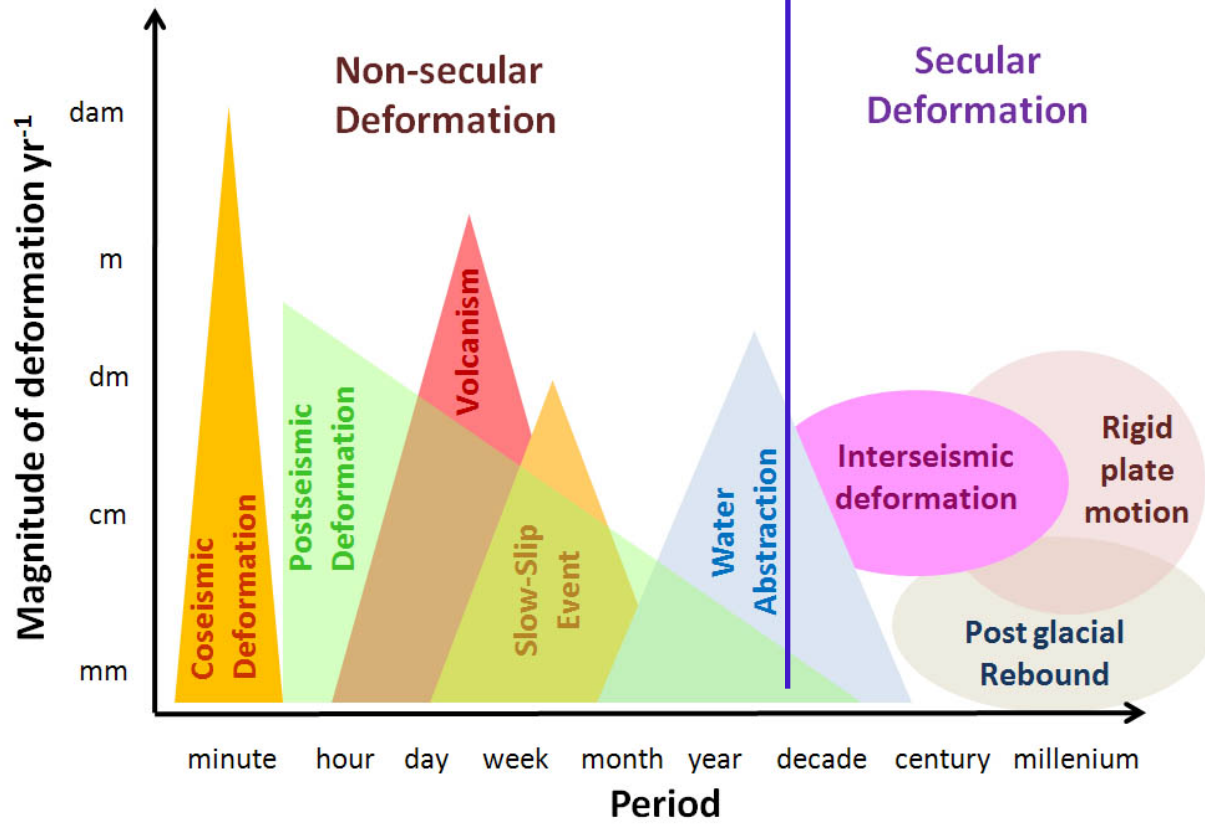
**Static or Semi-Dynamic Frame / Datum**  
(e.g. OSGB36, GDA94, NZGD2000, IGM95)

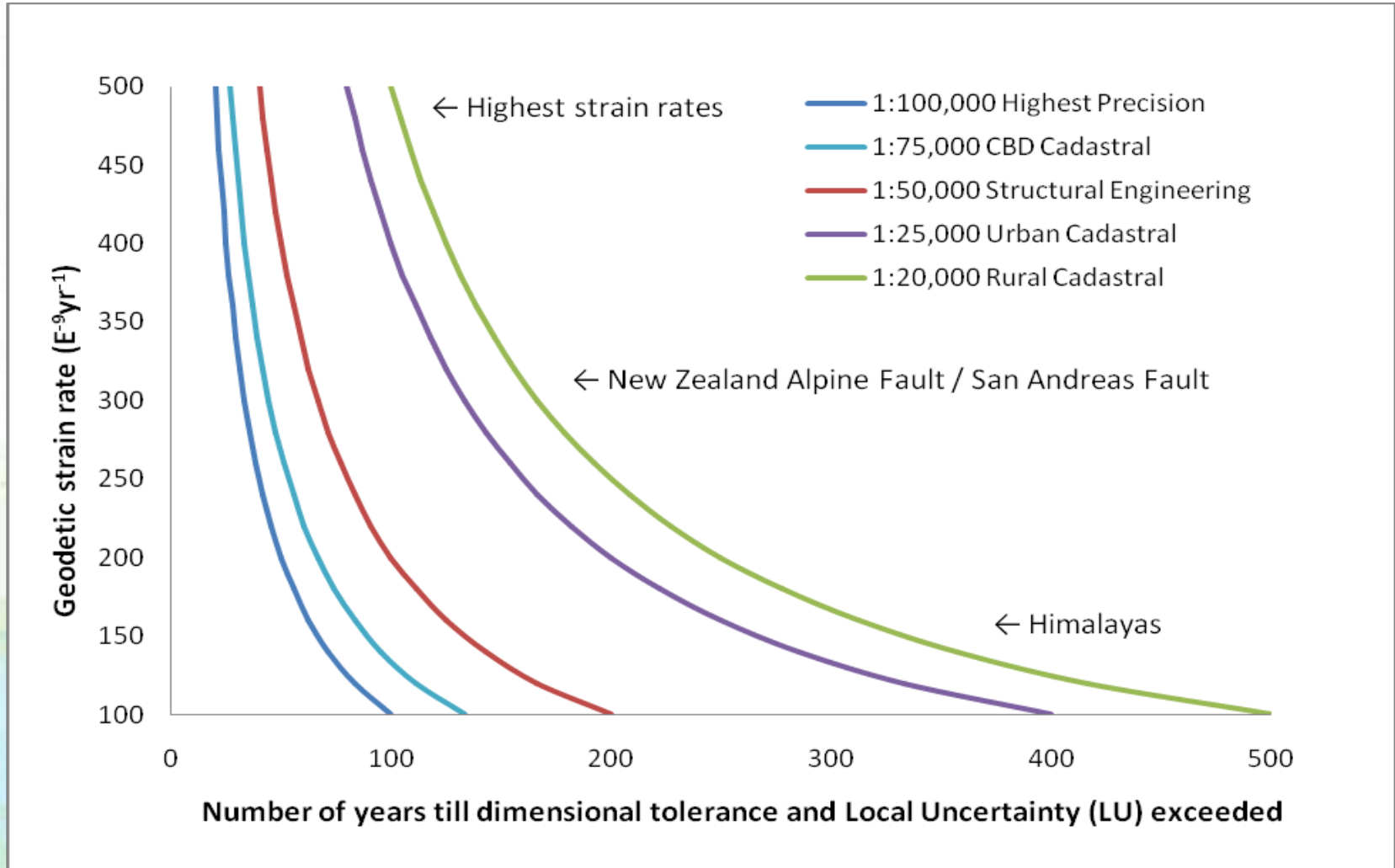
14 – parameter  
transformation  
and/or  
deformation  
model



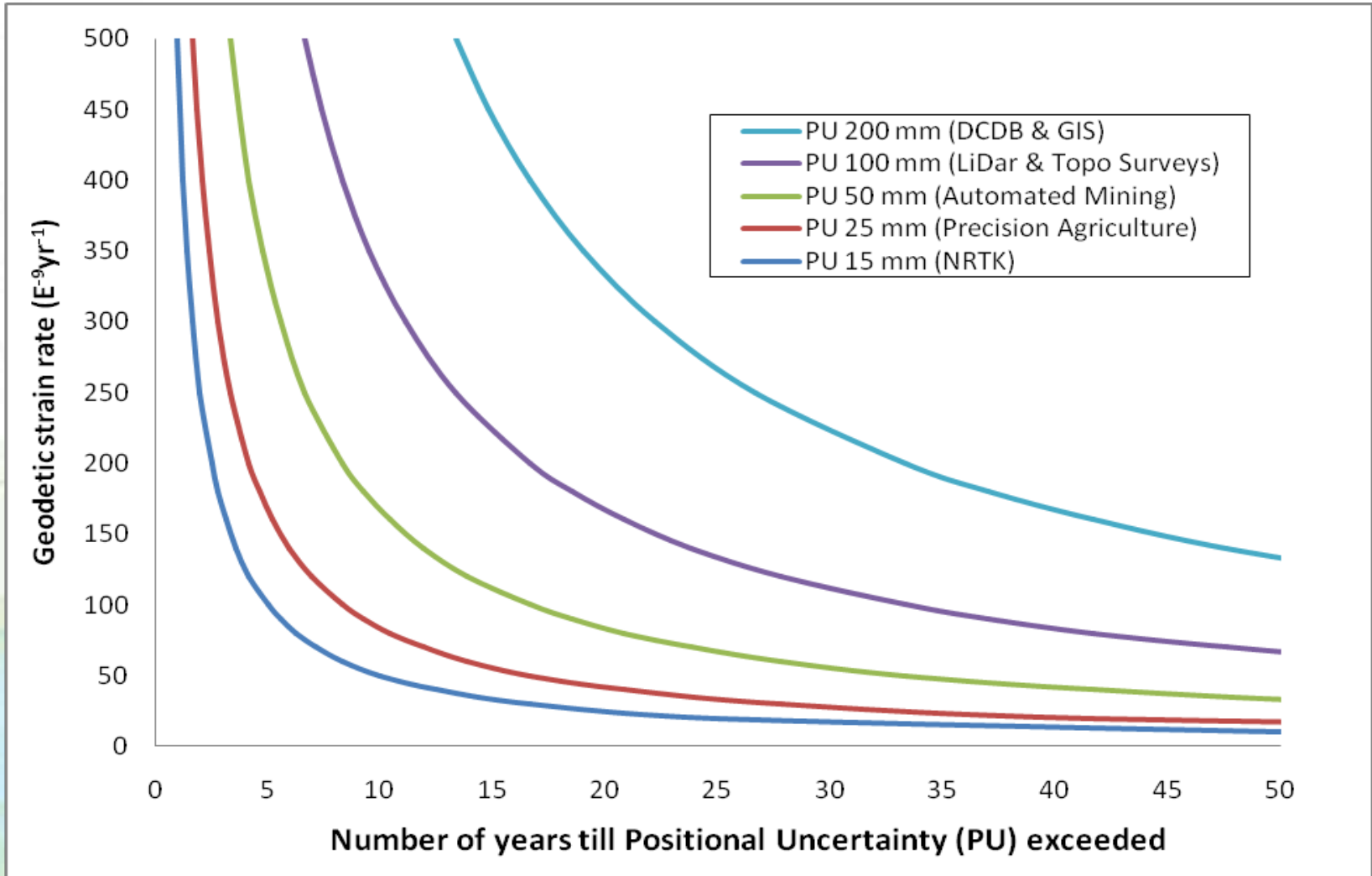
Results in changes in coordinates of local frame  
- patch model

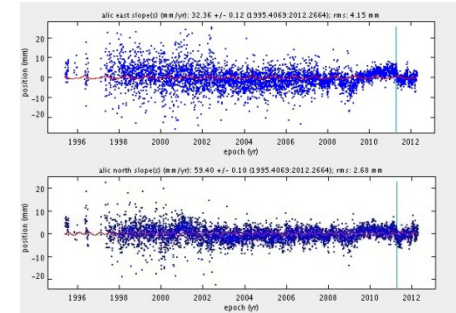
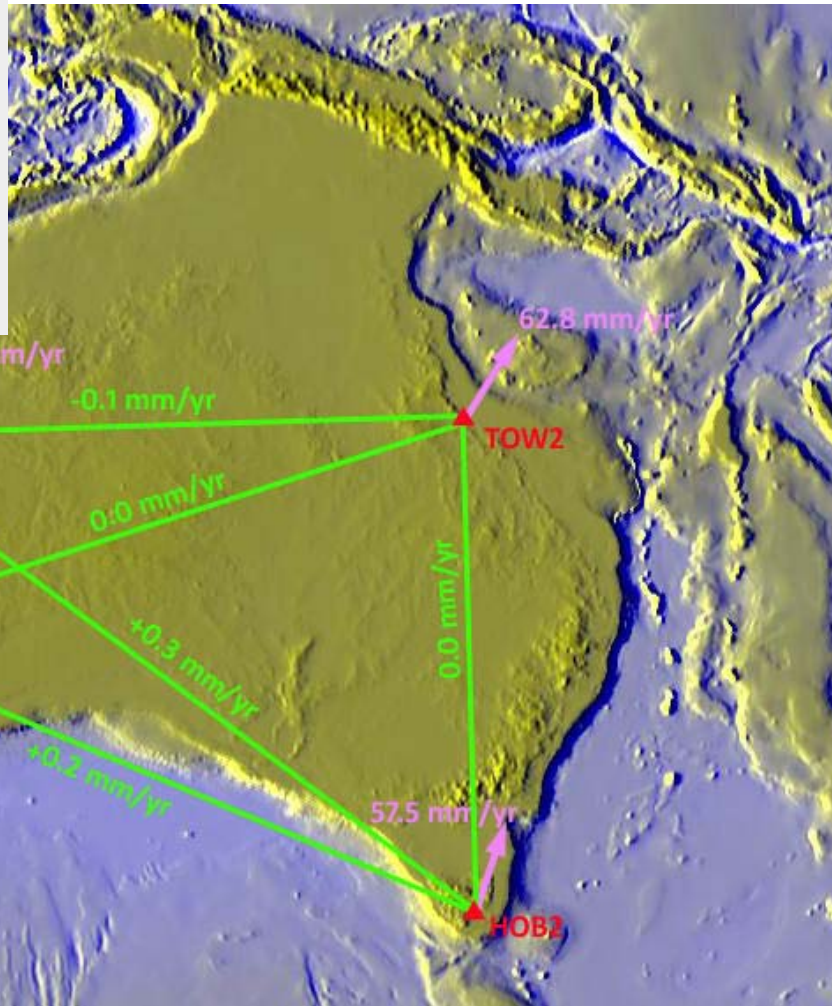
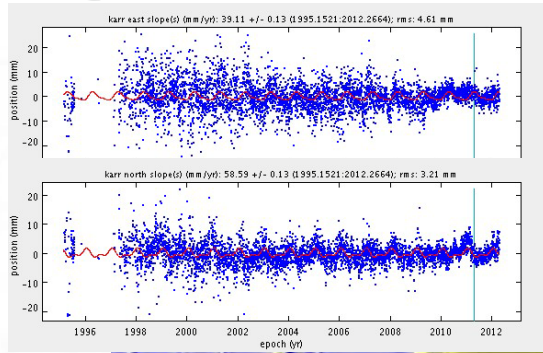
Deformation is “invisible” in local frame  
- secular model



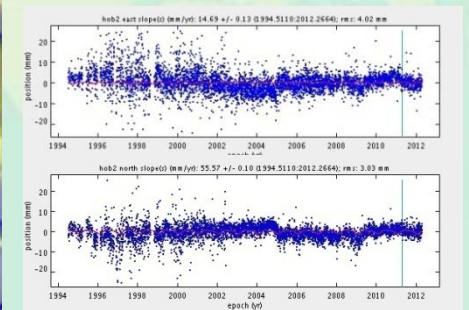


# Positional Tolerance vs Geodetic Deformation



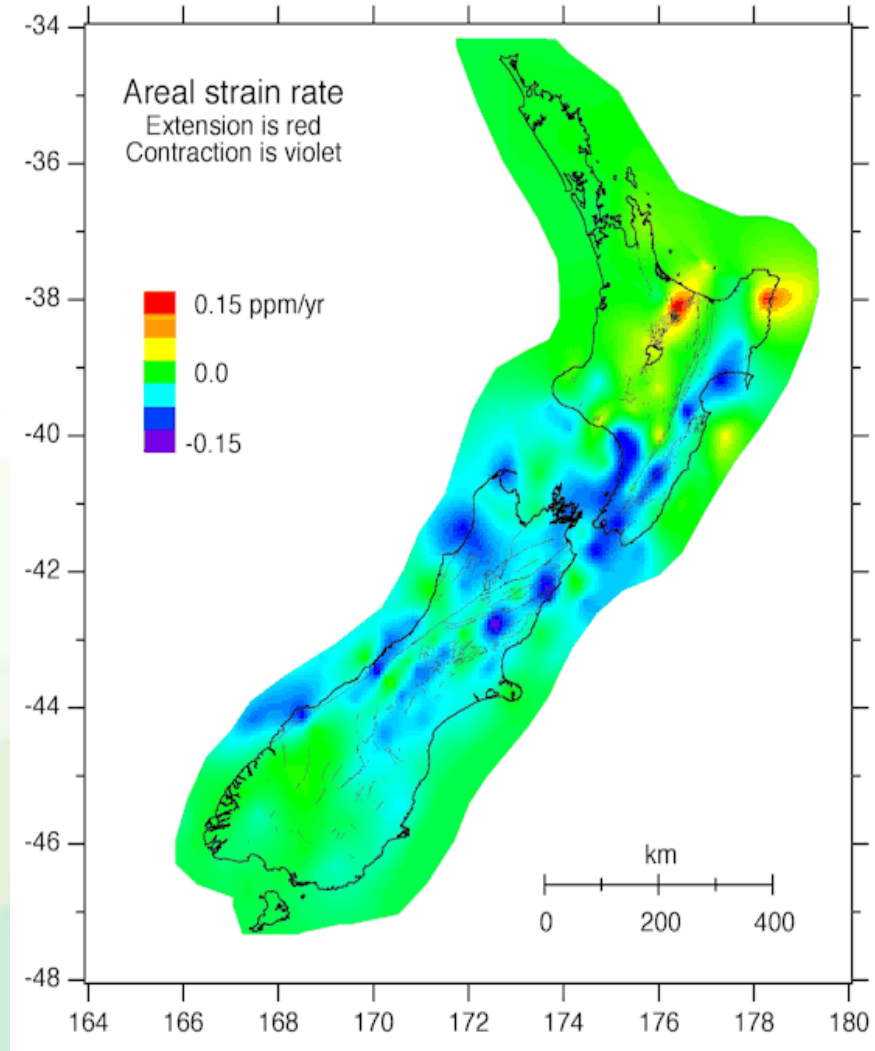
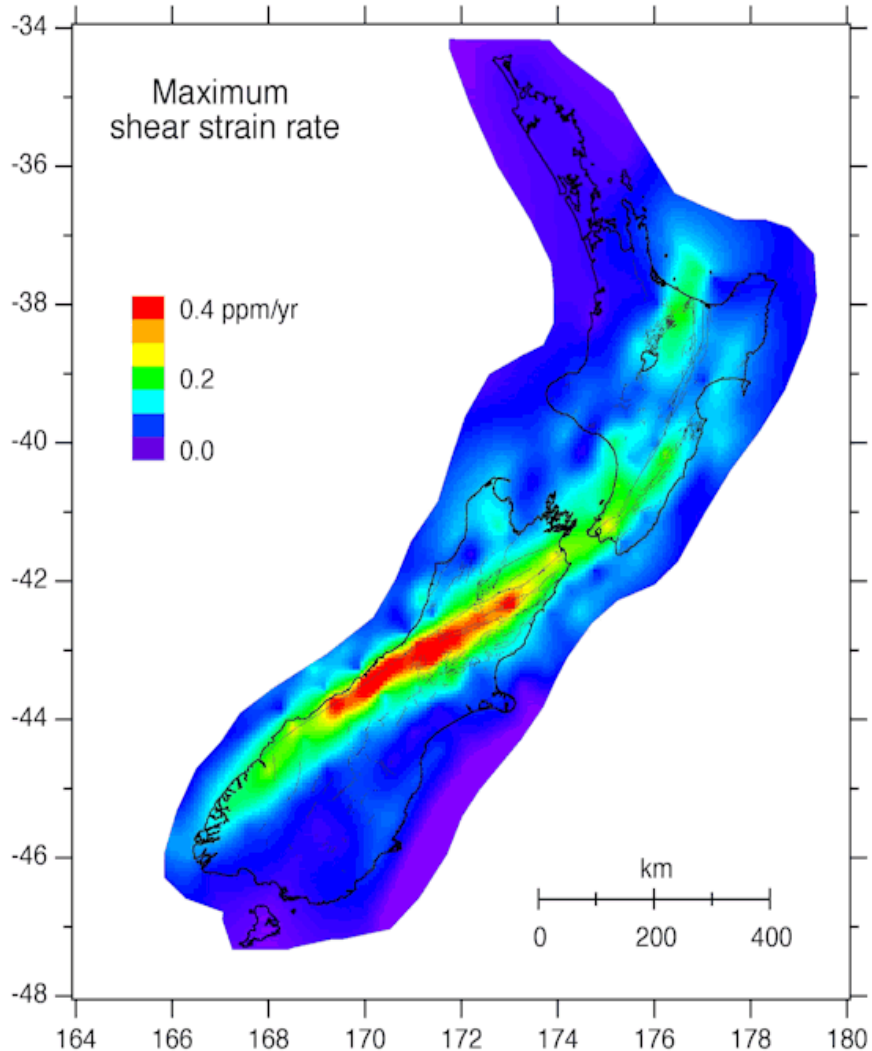


Time-series plots  
SCRIPPS, UCSD



purple arrows – tectonic movement, green lines – baseline changes per year

# Deformation in Plate Boundary Zones





**CORS + Campaign GNSS + Static local GNSS surveys**

**ITRF time-series**

**Secular component**

**Non-secular component**

**Plate rotation  
parameters**  
 $\Omega_x, \Omega_y, \Omega_z$

**Estimate Euler pole of network**  
– least squares inversion of site velocities

**test inversion – analyse residuals (observed minus modelled velocity)**

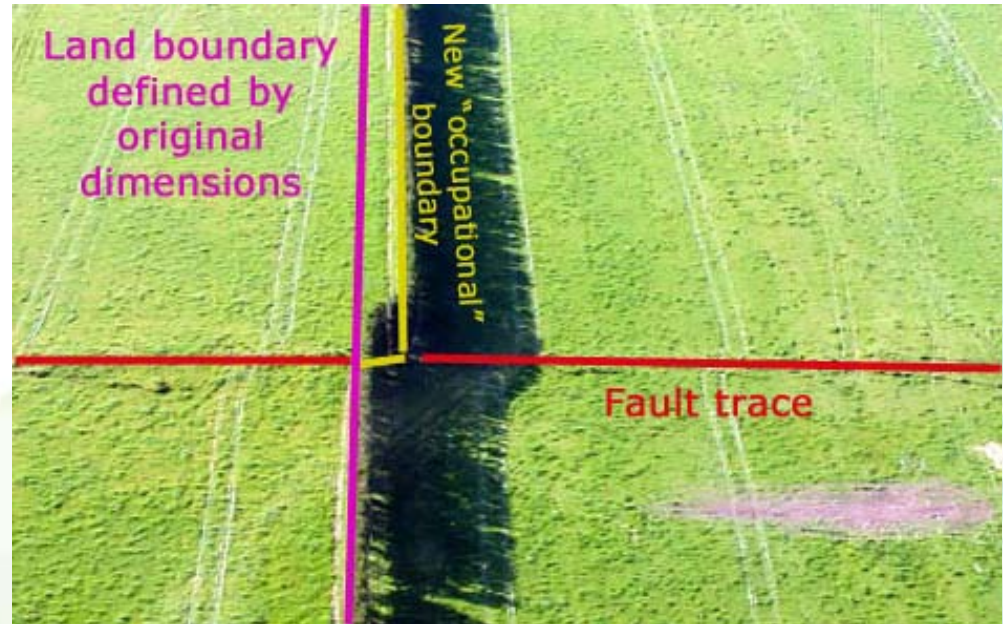
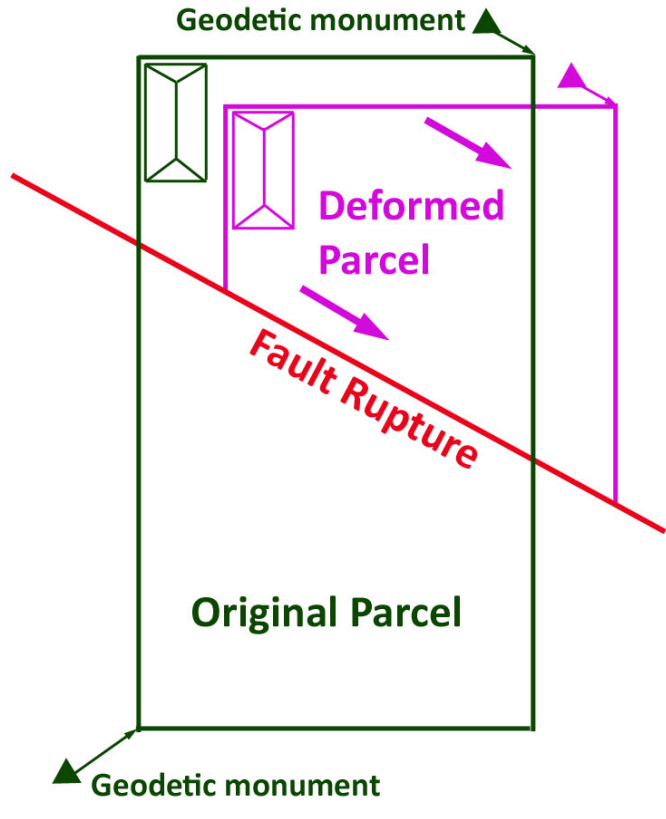
**Residual(s) within tolerance**  
- rigid network  
- no localised deformation

**Residual(s) exceed tolerance**  
- non rigid network, > 1 plates?  
- localised deformation?

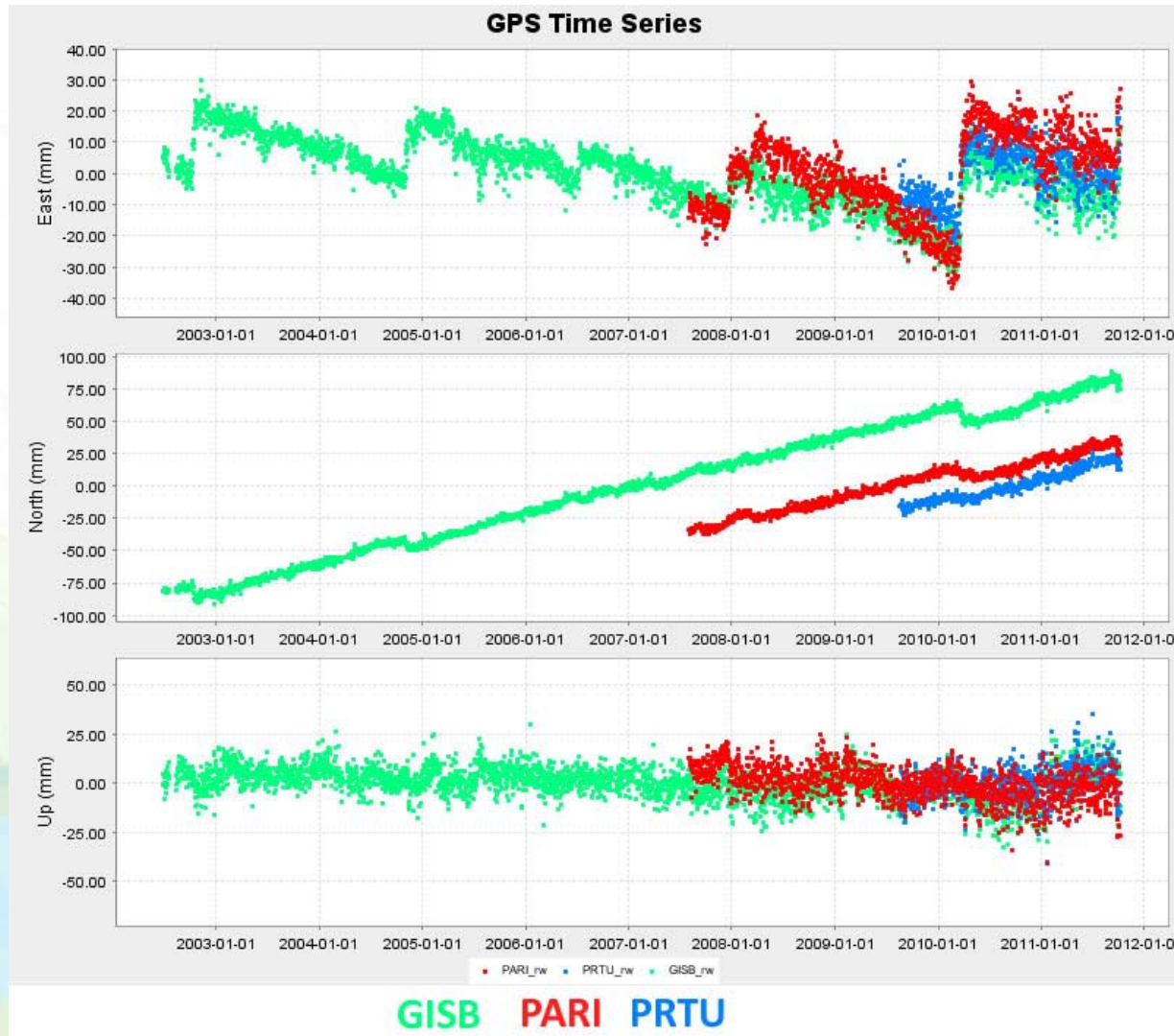
**Use Euler pole model**  
Compute 6 or 14 parameter model

**model locked faults – geodetic strain**

**Gridded – secular deformation model**

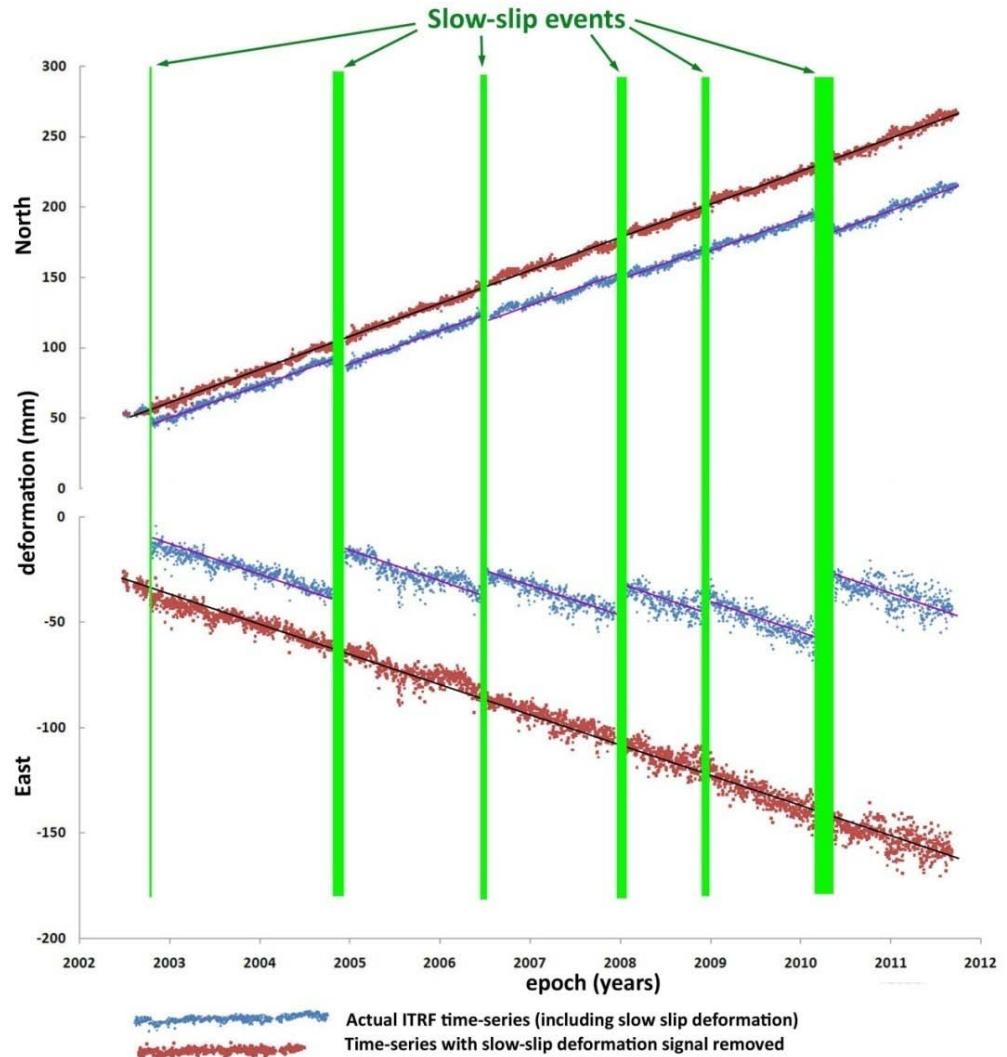


Localised deformation should result in coordinate changes to reflect visible reality



Separating seismic and secular (interseismic) deformation from time-series

Seismic patch is a sum of all non-secular (episodic) deformation between reference and measurement epoch



## Model Inputs –

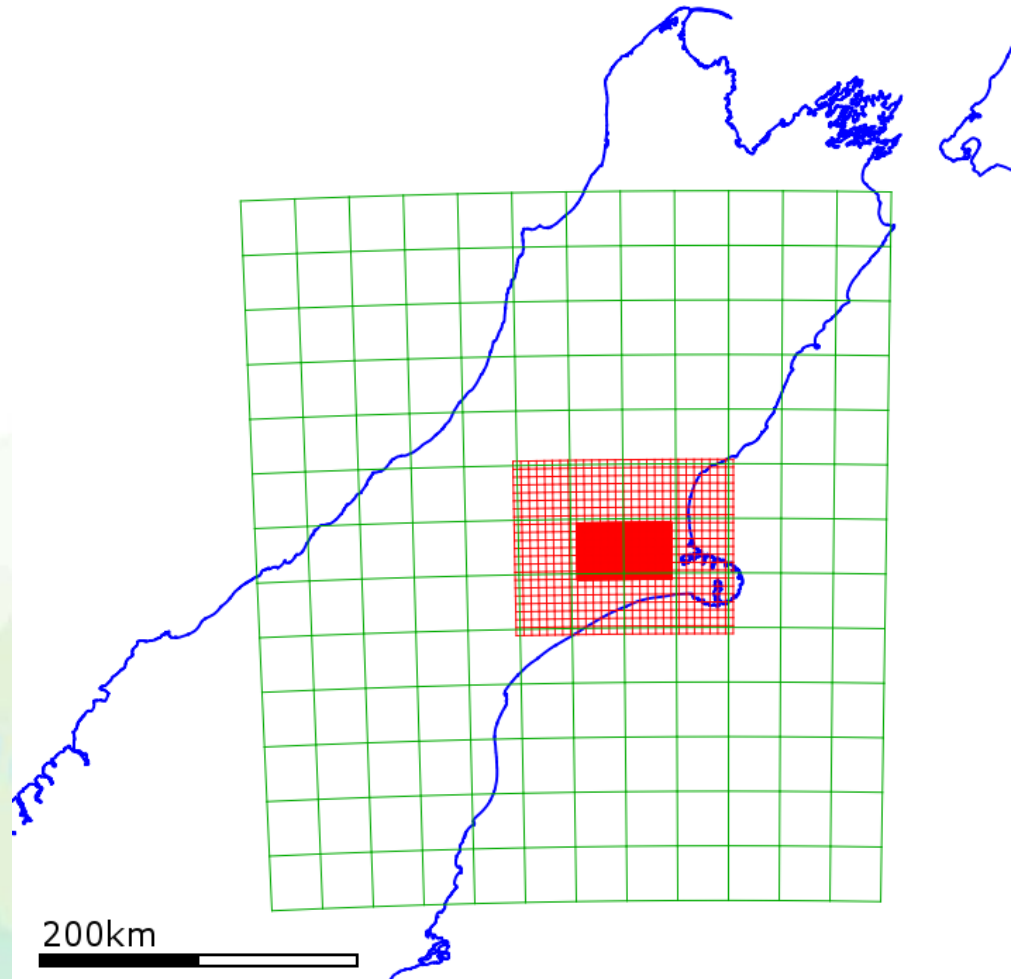
InSAR

LiDar & High-res imagery

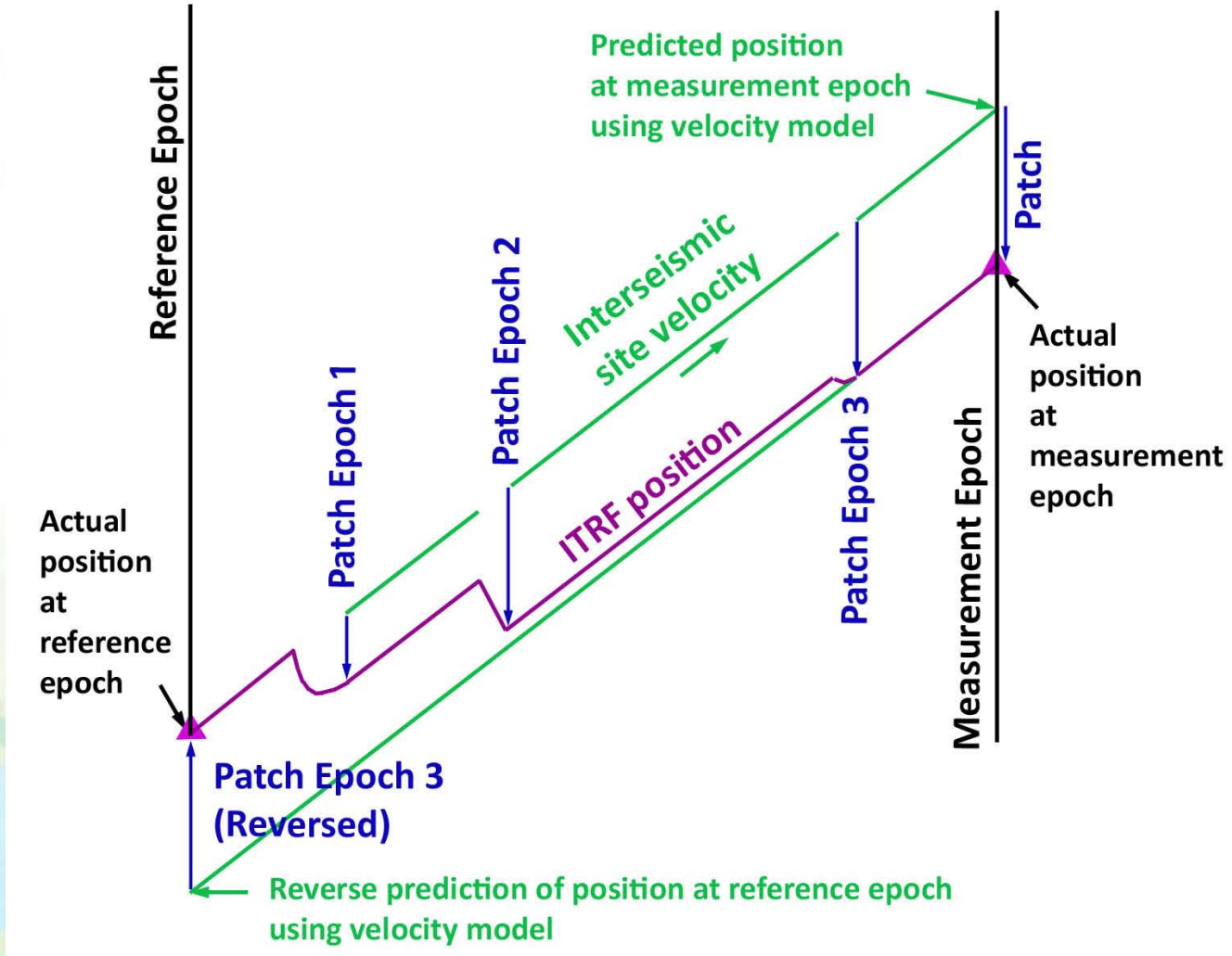
analysis of seismic  
data

Repeat GNSS  
obs of dense passive  
network  
*(Strong argument for  
maintaining passive  
geodetic infrastructure)*

Terrestrial surveys



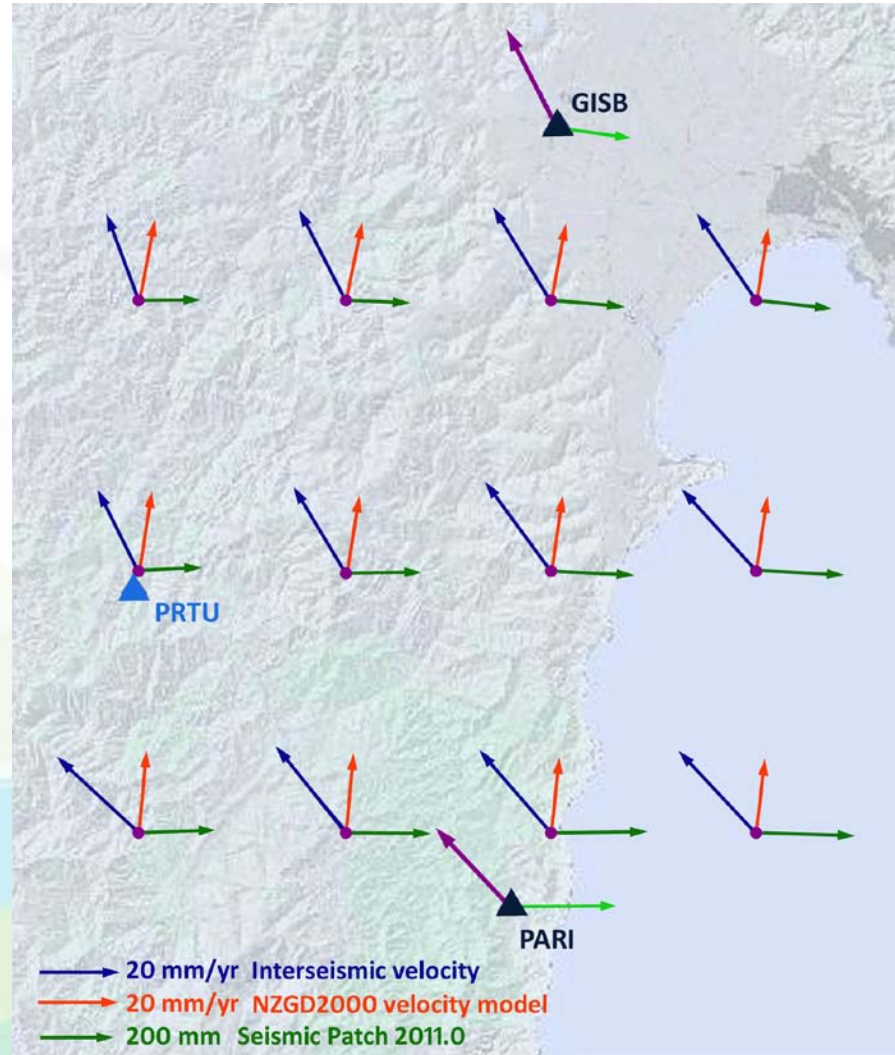
# Two modes of deformation - concept



**secular model  
(blue)**

**patch model  
(green)**

**existing model  
(orange)**



# Nouva Italia?!

